



KRONO-SAFE

Safe design in real-time



Synchronous Logical Execution Time: towards formal verification

Synchron'21

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Agenda

- **Context and motivation**
- **synchronous Logical Execution Time (sLET)**
- **The PsyC language**
- **Overview of the PsyC semantics**
- **Toward Formal Verification**
- **Conclusion/Perspectives**



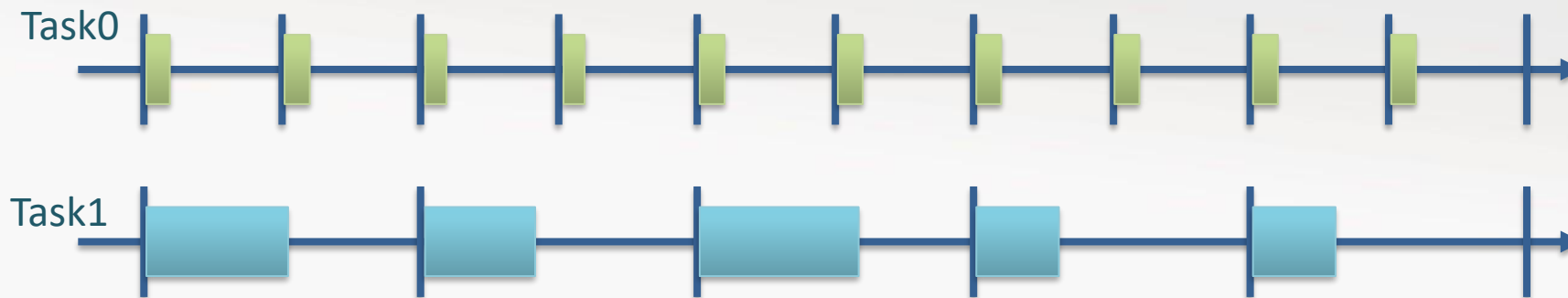
Safety-Critical Real-Time Systems

- **Krono-Safe:**
 - Software provider in the context of safety-critical systems
 - Domains: nuclear, avionics...
- **Certification issues:**
 - Predictability & Reproducibility
 - Temporal and functional requirements
- **Common solution:**
 - Use high-level deterministic formalisms
 - Verify high-level requirements using formal methods

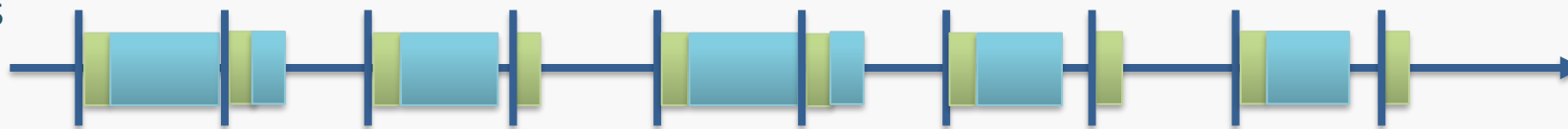


Motivation: modeling of real-time systems

- **Classical example: periodic real-time**



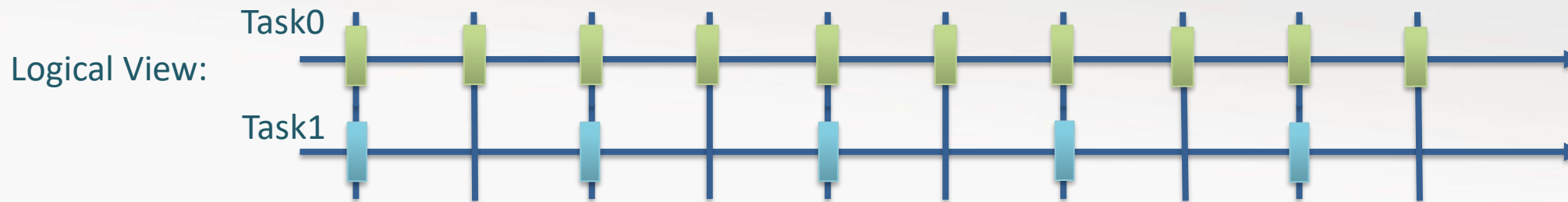
Scheduling
Tables





Motivation: modeling of real-time systems

- **The synchronous approach (Esterel, Lustre [1]):**
 - Model only activation in *logical time*



- **Traditional real-time interpretation:**

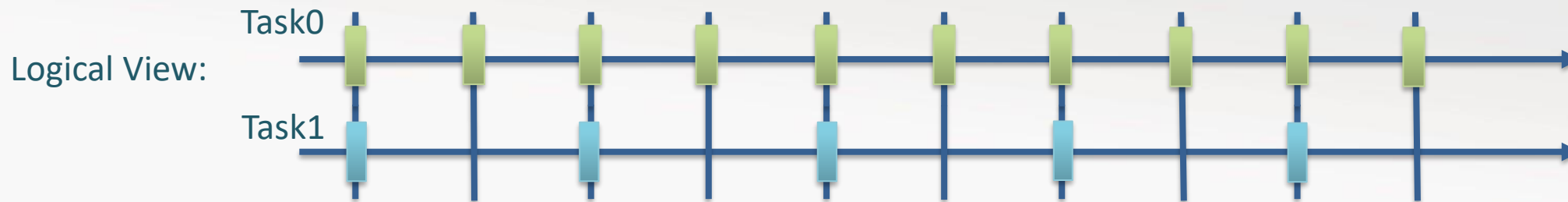
- Bind logical clocks to physical clocks (e.g. timer)
- Synchronous cycle computation can use all physical time until next cycle triggering



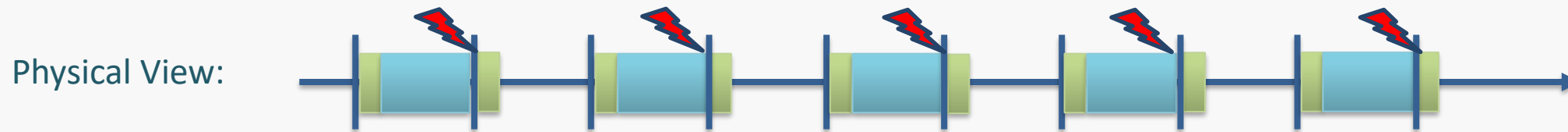


Motivation: modeling of real-time systems

- **Problem: modeling long-period tasks**
 - *Invisible in the synchronous model*



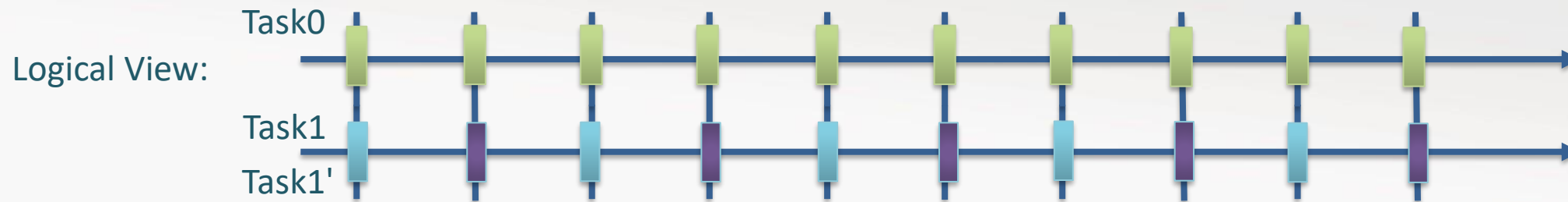
- Consider that the duration of task 2 is longer than the duration between successive cycle triggers:



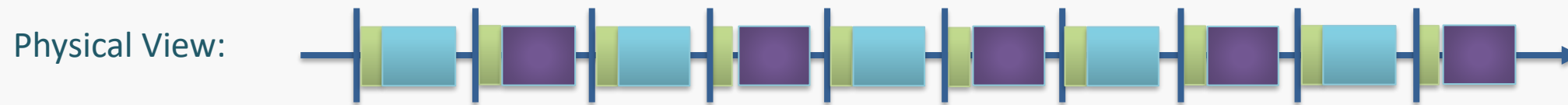


Motivation: modeling of real-time systems

- **Problem: modeling long-period tasks**
 - *Possible synchronous solution: retiming/slicing*



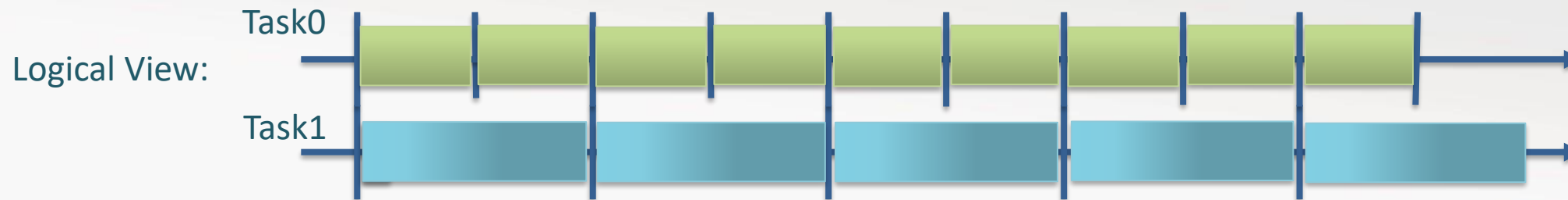
- **BUT: static and manual slicing is difficult and non-portable**





Motivation: modeling of real-time systems

- **Logical Execution Time [2]: extension of synchrony**
 - Specify the *logical time* cycle a task may span



- Classical synchronous composition is lost, but
- Real-time interpretation is more general
 - Contract separating application design and platform resource





The synchronous LET paradigm

- **A synchronous extension of LET: PsyC [4]**
 - Given a statement advance which fixes the bounds of a logical interval:

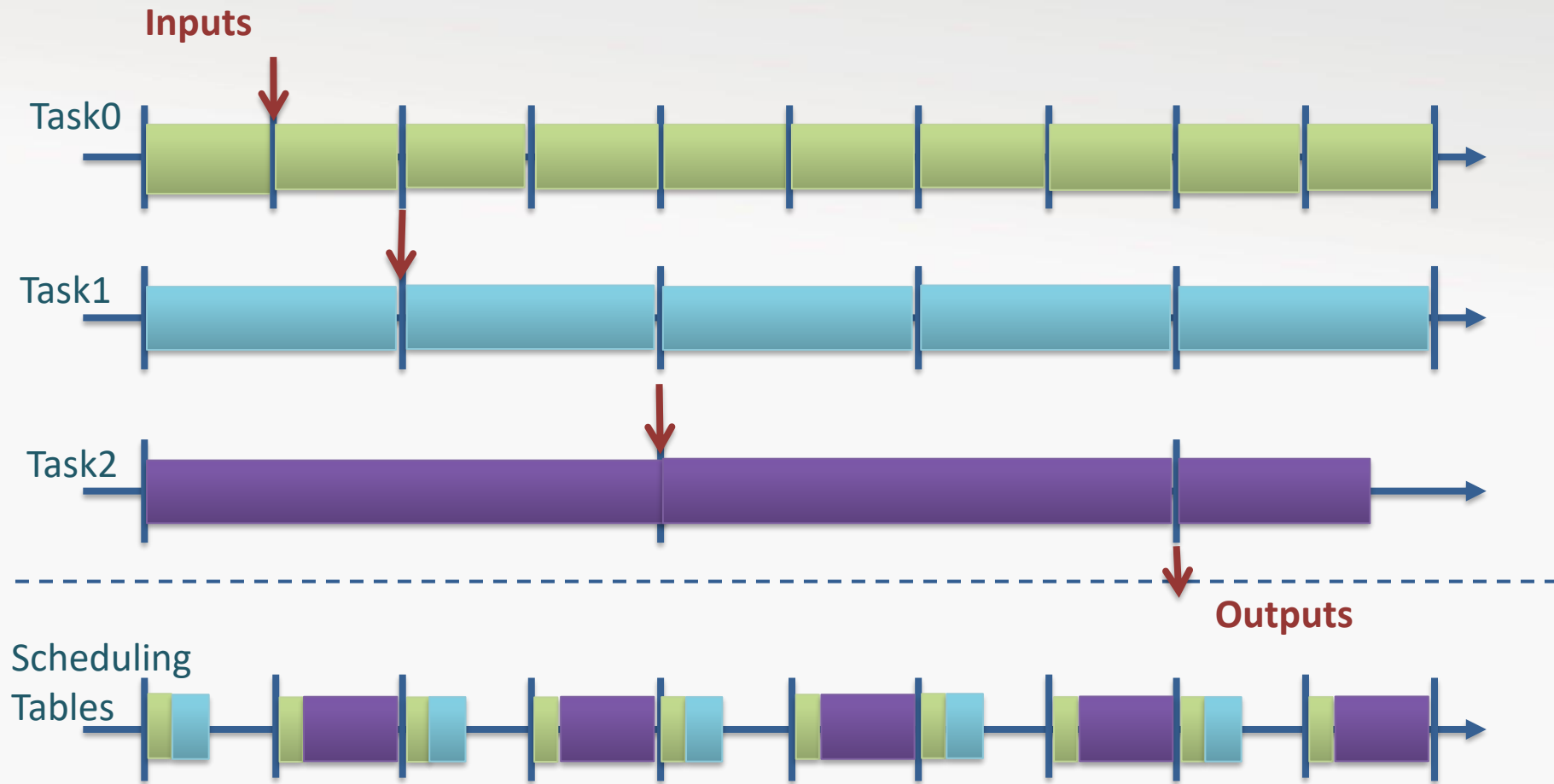
advance 5 with min;
advance 1 with hour \neq *advance 65 with min*

- Contrary to classical LET, time is not cumulative
- Bounds are relative to the ticks of some logical clocks



Logical Execution Time: temporal requirements

- A typical verification problem: end-to-end latencies [3]





The PsyC language: concepts

- **Primary temporal Sources**
 - generating global rhythms
 - most often, only one linked to real time
- **Periodic Clocks**
 - subdivising source ticks
- **Program reactions**
 - may span a fixed interval: sLET interval durations
- **Temporal variables**
 - share values between agents
 - persistent values and values updated on sLET interval bounds



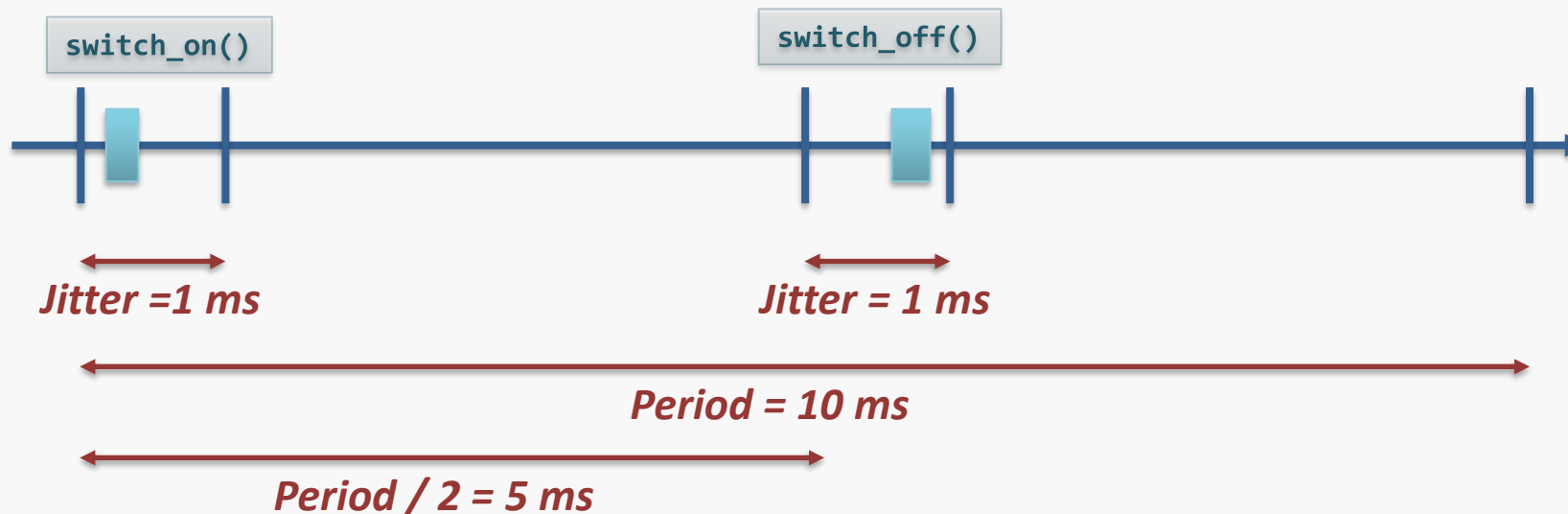
The PsyC language

- Produced by Krono-Safe, dedicated to the safety-critical real-time software integration.
 - Based on a technology developed by the CEA (Oasis and PharOS projects)
- Implement the (s)LET model
 - Enable a **deterministic** communication model
 - Allow complex, dynamic temporal behavior
- Extension of the C language:
 - Multiple concurrent agents with **functional** (C code) and **non-functional** parts (advance statement)
 - Temporal sources and clocks
 - Communication means



The PsyC language: a simple example

- **LED-blinking example – specification:**
 - Period = 10ms
 - Duty Cycle (ON) between 0.4 and 0.6
 - Switching jitter ≤ 1 ms

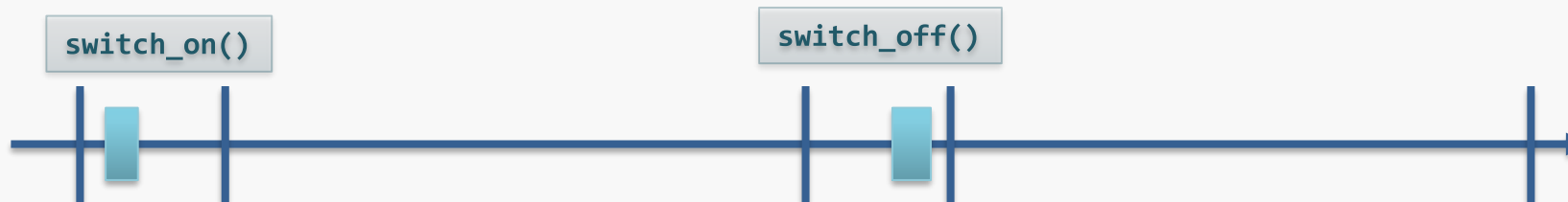




The PsyC language: a simple example

- LED-blinking example – PsyC code:

```
source realtime_ms;  
clock c_jitter = realtime_ms;  
clock c_half_period = 5*realtime_ms;  
clock c_period = 2*c_half_period;  
  
agent Blinker  
{  
  body start  
  {  
    switch_on();  
    advance 1 with c_jitter;  
    /* do nothing */  
    advance 1 with c_half_period;  
  
    switch_off();  
    advance 1 with c_jitter;  
    /* do nothing */  
    advance 1 with c_period;  
  }  
}
```





The PsyC language: a simple example

- LED-blinking example – PsyC code:

```
temporal mode = OK with c_ms;

agent Blinker {
  body start {
    if ($[0]mode == ERROR)
      jump blink;
    advance 1 with c_ms;
  }
  body blink {
    switch_on();
    advance 1 with c_jitter;
    /* do nothing */
    advance 1 with c_half_period;

    switch_off();
    advance 1 with c_jitter;
    /* do nothing */
    advance 1 with c_period;
  }
}
```



The PsyC language: a simple example

- LED-blinking example – PsyC code:

```
temporal mode = OK with c_ms;

agent Blinker {
  body start {
    if ($[0]mode == ERROR)
      jump blink;
    advance 1 with c_ms;
  }
  body blink {
    switch_on();
    advance 1 with c_jitter;
    /* do nothing */
    advance 1 with c_half_period;

    switch_off();
    advance 1 with c_jitter;
    /* do nothing */
    advance 1 with c_period;
  }
}
```

```
agent ErrorManager {
  body start {
    if (/* some condition ... */)
      mode = ERROR;
    advance 1 with c_ms;
  }
}
```



The PsyC semantics: abstract syntax

- Syntax overview:

decl ::= *clk* | *agt* | ... (*coms*)
clk ::= *source c* | *clock c = n₁ × c_p + n₂*
agt ::= *agent id body⁺*
body ::= *body id stmt*



The PsyC semantics: abstract syntax

- Syntax overview:

stmt ::=

- | *id := expr*
- | *stmt₁; stmt₂*
- | *advance n with c*
- | *if expr then stmt₁ else stmt₂*
- | ...



The PsyC semantics: Esterel translation

- **Esterel translation:**
 - **Synchronous interpretation of PsyC**
 - Semantics through translation
 - Allow to re-use existing tools
 - **Both PsyC and Esterel are imperative and control-flow**
 - **Main ideas:**
 - Clock ticks are signals
 - Advance are await
 - Local variables are Esterel variables
 - Temporal variables are valued signals



The PsyC semantics: Esterel translation

- Esterel Translation: clocks

$$T(\mathit{clock } c = p * c_p + o) \stackrel{\text{def}}{=} \begin{array}{l} \mathit{await } o; \\ \mathit{loop} \\ \quad \mathit{emit } c \\ \quad \mathit{each } p c_p \end{array}$$



The PsyC semantics: Esterel translation

- Esterel Translation: agent statements

$$T(id := expr) \stackrel{\text{def}}{=} id := T(expr)$$

$$T(stmt_1; stmt_2) \stackrel{\text{def}}{=} T(stmt_1); T(stmt_2)$$

$$T(\text{if } expr \text{ then } s_1 \text{ else } s_2) \stackrel{\text{def}}{=} \text{if } T(expr) \text{ then } T(s_1) \text{ else } T(s_2)$$

$$T(\text{advance } n \text{ with } c) \stackrel{\text{def}}{=} \text{await } n \text{ c; run } UpdateOutputs(vars \dots)$$

– *UpdateOutputs* emit valued signals for each local variable



Toward Formal Verification

- **Global methodology:**
 - Model properties as synchronous observers in Esterel [5]
- **Example:**

```
/* blinker start body */  
loop  
[  
  if ?mode = ERROR then  
    next_body := blink;  
    exit body;  
  await 1 c_ms;  
]
```

```
private_mode := OK;  
/* error manager start body */  
loop  
[  
  if /* some condition */ then  
    private_mode := ERROR;  
    await 1 c_ms;  
    emit mode(private_mode);  
]
```



Toward Formal Verification

- **Global methodology:**
 - Model properties as synchronous observers in Esterel [5]
- **Example:**

```
/* blinker blink body */  
loop  
[  
  /* switch_on() */  
  await 1 c_jitter;  
  await 1 c_half_period;  
  /* switch_off(); ... */  
  await 1 c_jitter;  
  await 1 c_period;  
]
```




Toward Formal Verification

- **Global methodology:**
 - Model properties as synchronous observers in Esterel [5]
- **Example: minimum duty-cycle (≥ 4 ms)**

```
/* blinker blink body */  
loop  
[  
  /* switch_on() */  
  await 1 c_jitter;  
  abort  
    await 1 c_half_period;  
    emit ERROR;  
  when 4 realtime_ms;  
  /* switch_off(); ... */  
]
```



Conclusion and Perspectives

- **Sum-up:**
 - Logical Execution Time extends synchrony with logical durations
 - Synchronous interpretation of Logical Execution Time with PsyC
- **In practice in industry:**
 - (s)LET languages are usually used as integration/coordination language:
 - i.e. software integration of synchronous (functional) components
- **Perspectives:**
 - Model more complex properties (e.g. end-to-end latencies)
 - Optimize to only represent « noticeable » instants: primary for efficient verification



References

- [1] A. Benveniste, P. Caspi, S. Edwards, N. Halbwachs, P. Guernic, and R. Simone, “The Synchronous Languages 12 Years Later,” *Proceedings of the IEEE*, vol. 91, pp. 64–83, Feb. 2003, doi: [10.1109/JPROC.2002.805826](https://doi.org/10.1109/JPROC.2002.805826).
- [2] C. M. Kirsch and A. Sokolova, “The Logical Execution Time Paradigm,” in *Advances in Real-Time Systems*, S. Chakraborty and J. Eberspächer, Eds. Berlin, Heidelberg: Springer, 2012, pp. 103–120. doi: [10.1007/978-3-642-24349-3_5](https://doi.org/10.1007/978-3-642-24349-3_5).
- [3] R. Wyss, F. Boniol, C. Pagetti, and J. Forget, “End-to-end latency computation in a multi-periodic design,” in *Proceedings of the 28th Annual ACM Symposium on Applied Computing - SAC '13*, Coimbra, Portugal, 2013, p. 1682. doi: [10.1145/2480362.2480678](https://doi.org/10.1145/2480362.2480678).
- [4] C. Aussagues, C. Cordonnier, M. Aji, V. David, and J. Delcoigne, “OASIS: A New Way to Design Safety Critical Applications,” *IFAC Proceedings Volumes*, vol. 29, no. 5, pp. 21–26, Nov. 1996, doi: [10.1016/S1474-6670\(17\)46349-X](https://doi.org/10.1016/S1474-6670(17)46349-X).
- [5] N. Halbwachs, F. Lagnier, and P. Raymond, “Synchronous Observers and the Verification of Reactive Systems,” in *Algebraic Methodology and Software Technology (AMAST'93)*, London, 1994, pp. 83–96. doi: [10.1007/978-1-4471-3227-1_8](https://doi.org/10.1007/978-1-4471-3227-1_8).